

TOUCHCAM: REALTIME RECOGNITION OF LOCATION-SPECIFIC ON-BODY GESTURES TO SUPPORT USERS WITH VISUAL IMPAIRMENTS

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ON-BODY INTERACTION – DEFINITION


A type of interaction technique which employs the **user's own body** as an **interactive surface**

ON-BODY INTERACTION – BENEFITS

A person wearing a white long-sleeved shirt and blue denim jeans is shown from the waist up. They are holding a white smartphone behind their back with their right hand, demonstrating on-body interaction. The background is a solid dark grey.

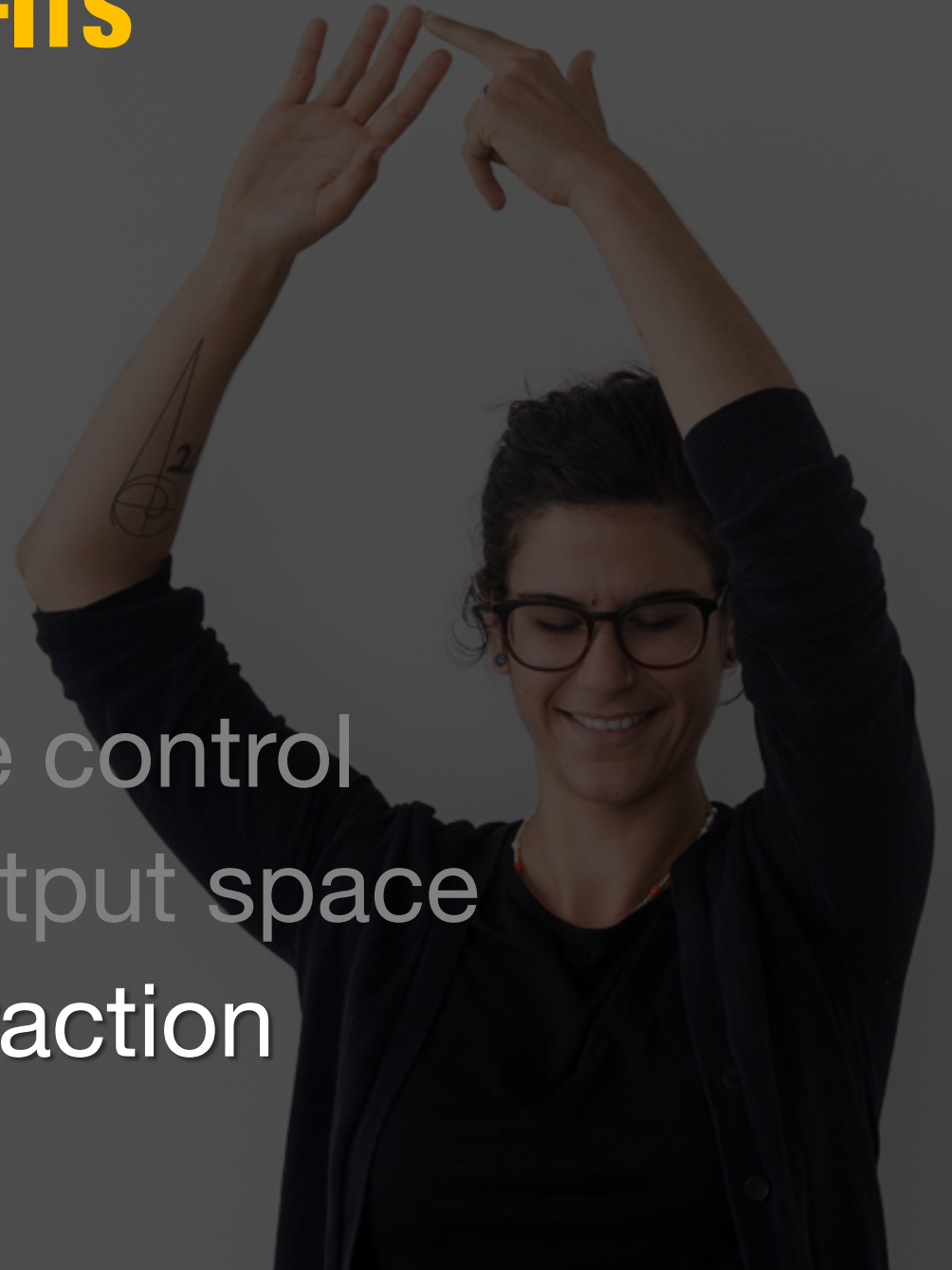
(+) Always-available control

ON-BODY INTERACTION – BENEFITS

- 
- (+) Always-available control
 - (+) Expanded input/output space

ON-BODY INTERACTION – BENEFITS

- (+) Always-available control
- (+) Expanded input/output space
- (+) Eyes-free Interaction



ON-BODY INPUT SENSING – APPROACHES

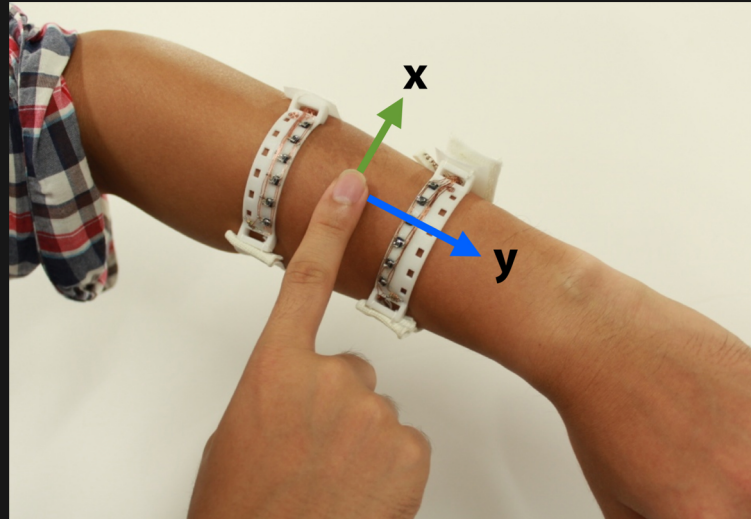
- Capacitive



Touché [Sato et al. (2012)] (left), iSkin [Weigel et al. (2015)] (right)

ON-BODY INPUT SENSING – APPROACHES

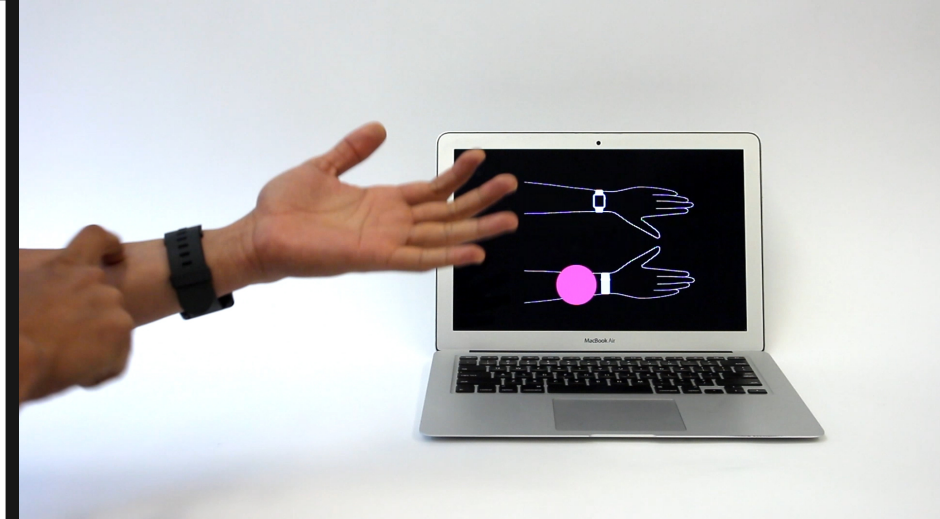
- Capacitive
- Infrared Reflective



SenSkin [Ogata et al. (2013)] (left), PalmGesture [Wang et al. (2015)] (right)

ON-BODY INPUT SENSING – APPROACHES

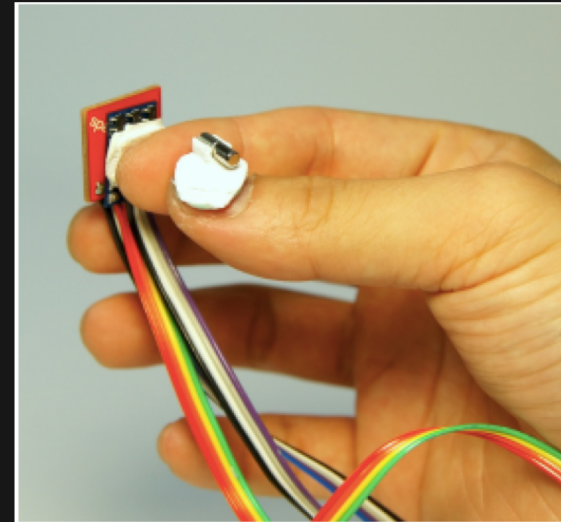
- Capacitive
- Infrared Reflective
- Bio-acoustic



Skinput [Harrison et al. (2010)] (left), ViBand [Gierad et al. (2016)] (right)

ON-BODY INPUT SENSING – APPROACHES

- Capacitive
- Infrared Reflective
- Bio-acoustic
- (Electro) Magnetic



Fingerpad [Chan et al. (2013)] (left), SkinTrack [Zhang et al. (2016)] (right)

ON-BODY INPUT SENSING – APPROACHES

- Capacitive
- Infrared Reflective
- Bio-acoustic
- (Electro) Magnetic
- Optic

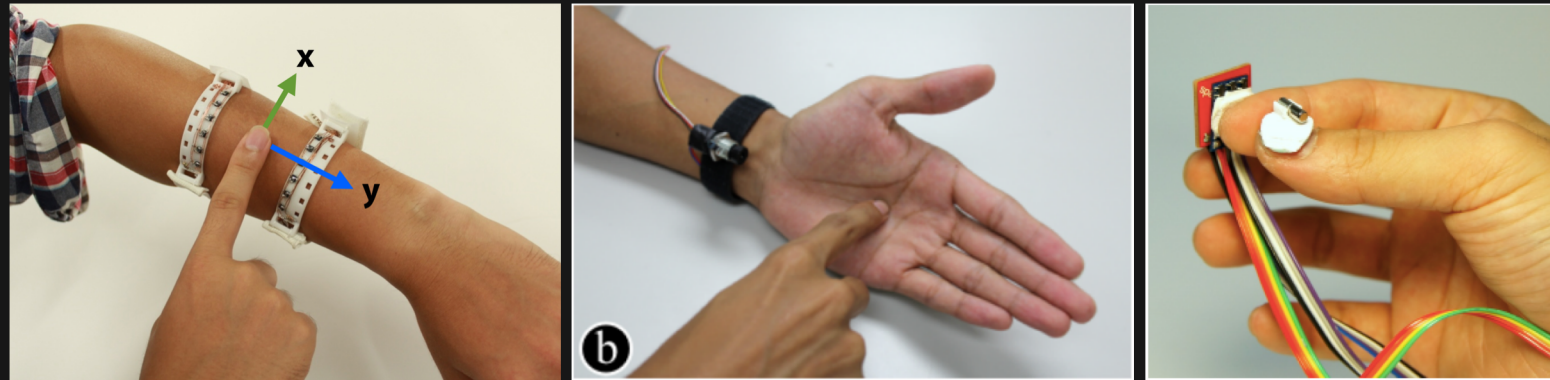


Imaginary Phone [Gustafson et al. (2011)] (left), OmniTouch [Harrison et al. (2011)] (right)

ON-BODY INPUT SENSING – LIMITATIONS

1. Interaction space

- Small and fixed area
- Single location



ON-BODY INPUT SENSING – LIMITATIONS

1. Interaction space

2. Input vocabulary

- Input localization only
- Gesture recognition only



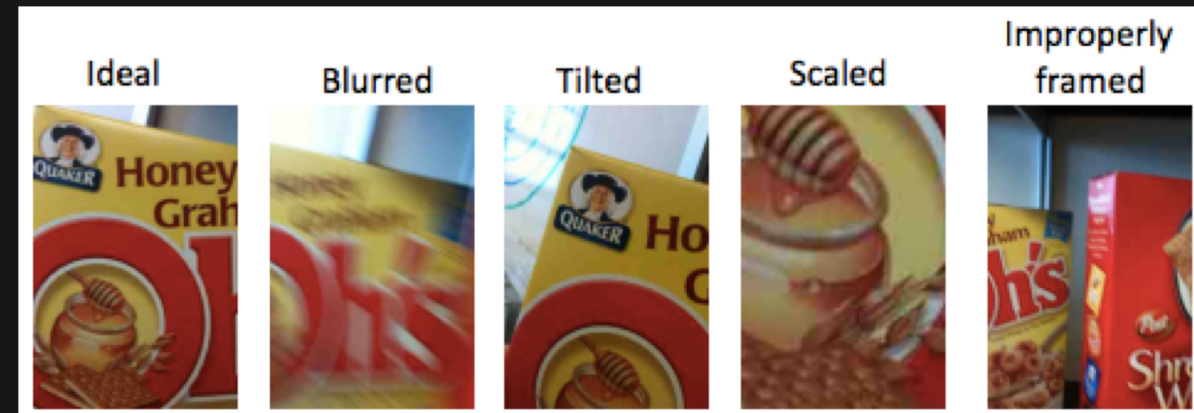
ON-BODY INPUT SENSING – LIMITATIONS

1. Interaction space
2. Input vocabulary
3. Sensing & touching locations



ON-BODY INPUT SENSING – LIMITATIONS

1. Interaction space
2. Input vocabulary
3. Sensing & touching locations
 - E.g., Camera for people with visual impairments



Example pictures taken by people with visual impairments [Bigham et al. (2010)]

ON-BODY INPUT SENSING – LIMITATIONS

1. Interaction space
2. Input vocabulary
3. Sensing & touching locations
4. **Target user**
 - Designed and evaluated for typical users only



OUR APPROACH: ON-BODY INPUT RECOGNITION USING **FINGER-WORN SENSORS**



OUR APPROACH: ON-BODY INPUT RECOGNITION Using **FINGER-WORN SENSORS**



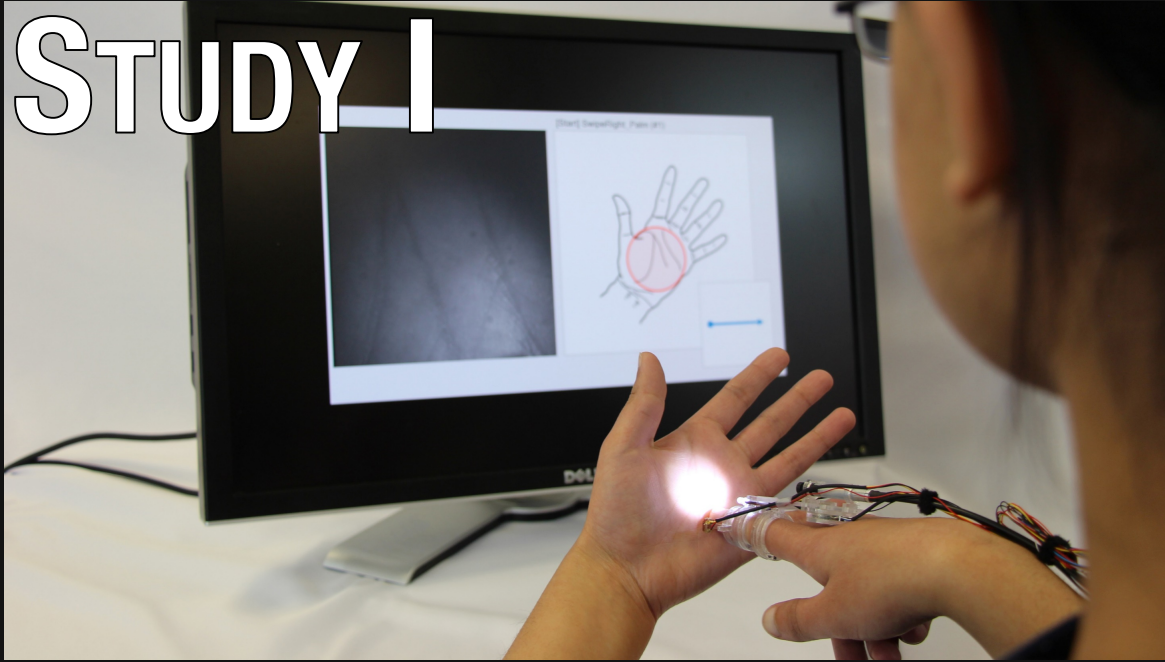
Advantages

1. Flexible input locations
2. Larger input vocabulary
3. Simplified sensing and processing



TOUCHCAM – METHODS

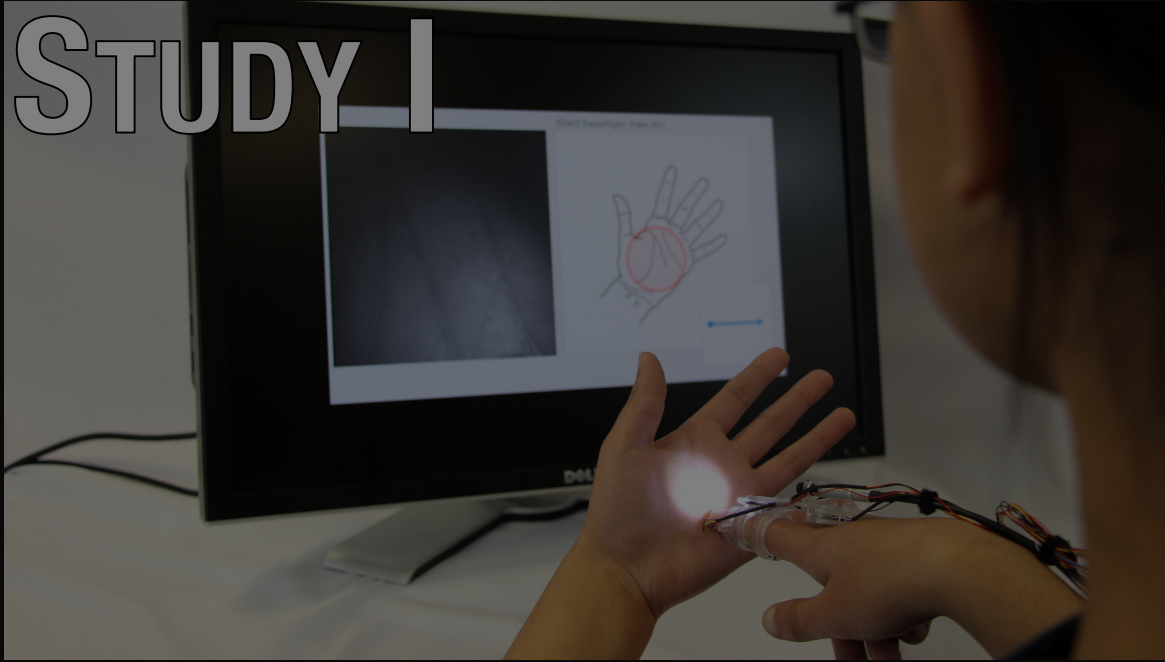
STUDY I



- Goal: to assess the feasibility

TOUCHCAM – METHODS

STUDY I



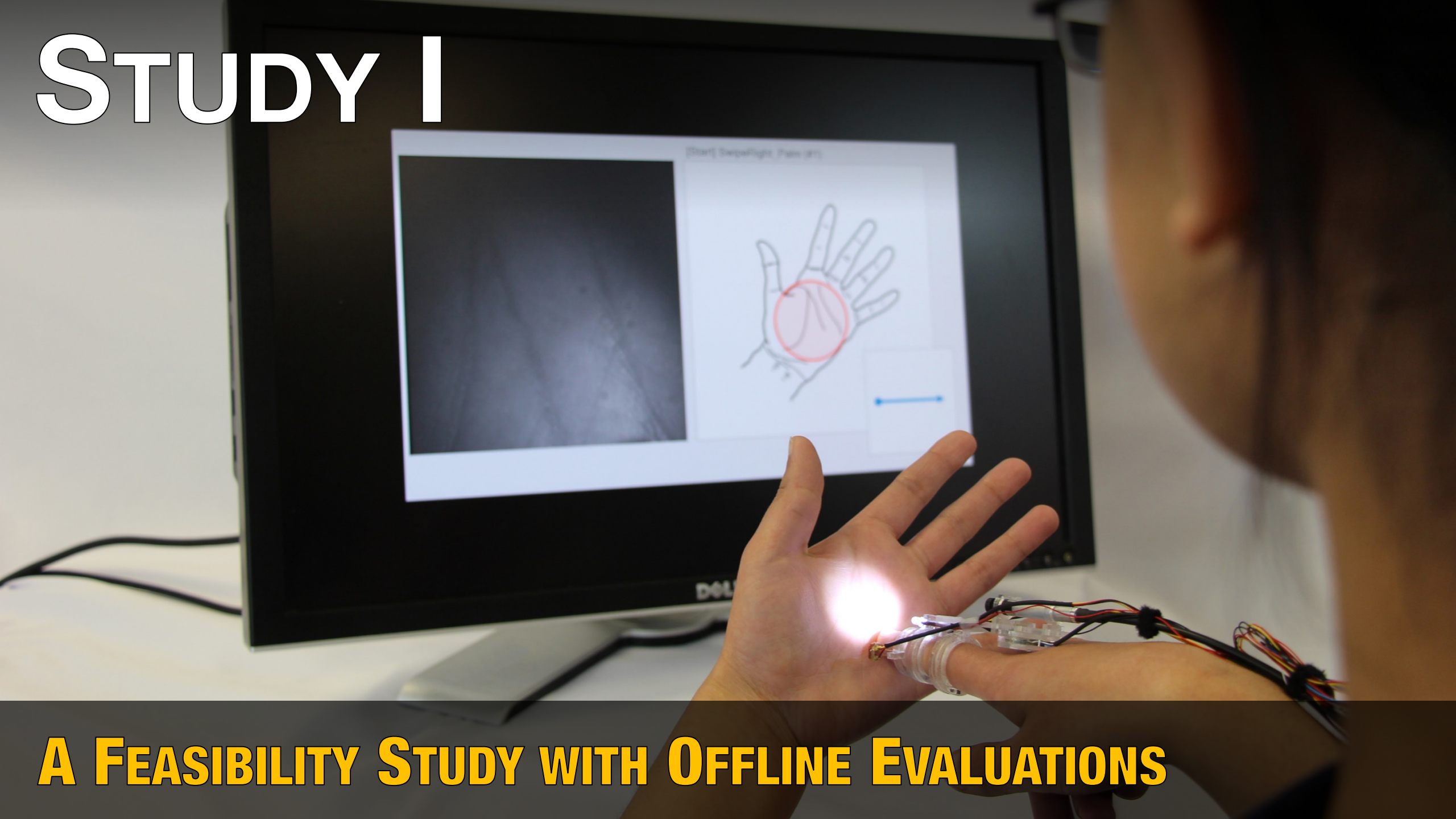
- Goal: to assess the feasibility

STUDY II



- Goal: to evaluate the usability

STUDY I



A FEASIBILITY STUDY WITH OFFLINE EVALUATIONS

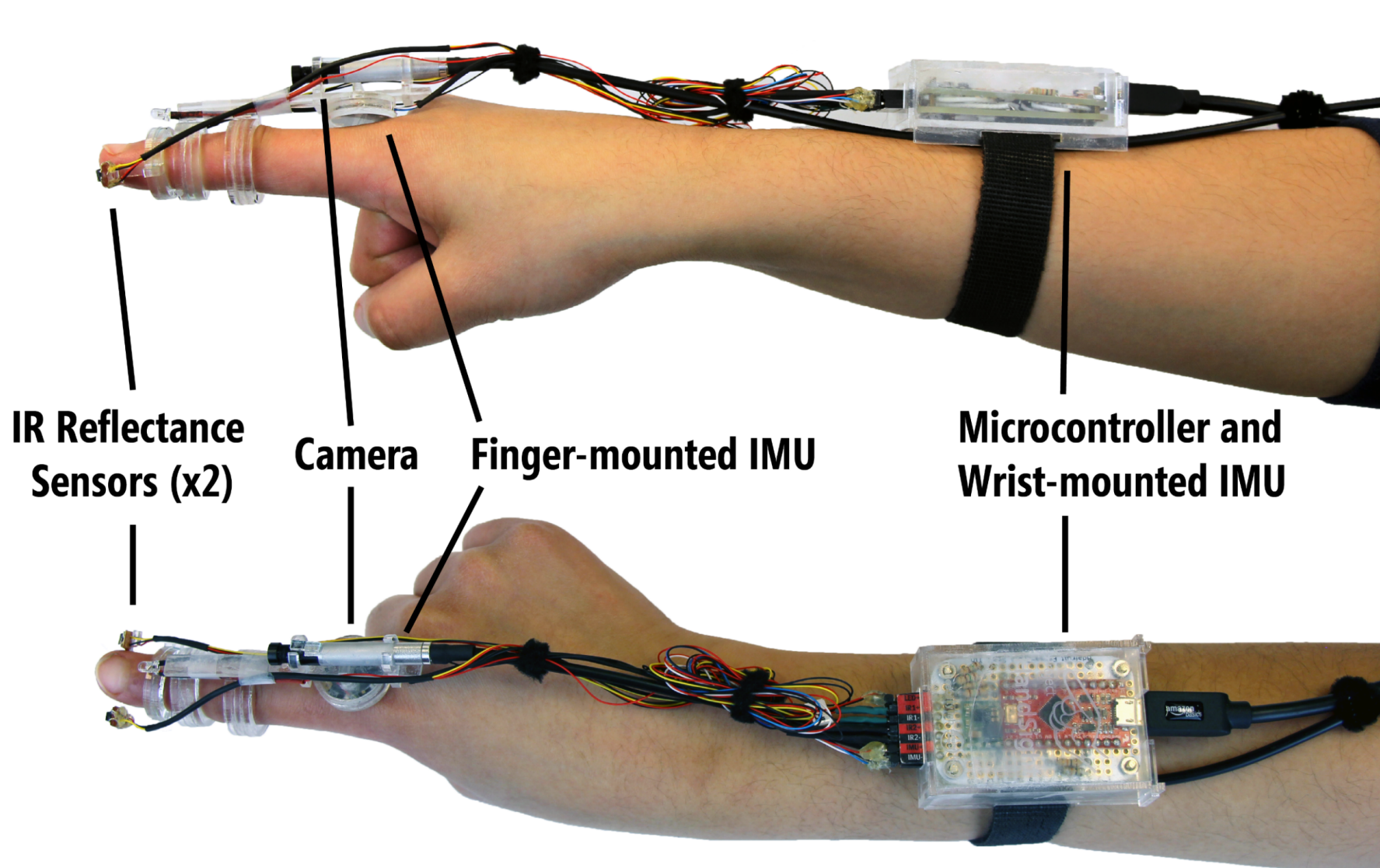
STUDY I

PARTICIPANTS

- **The number of subjects:**
 - 24 (16 female, 8 male)
- **Avg. age:**
 - 28.9 ($SD = 7.95$, range: 19 - 51)
- **Level of vision:**
 - Normal or corrected-to-normal

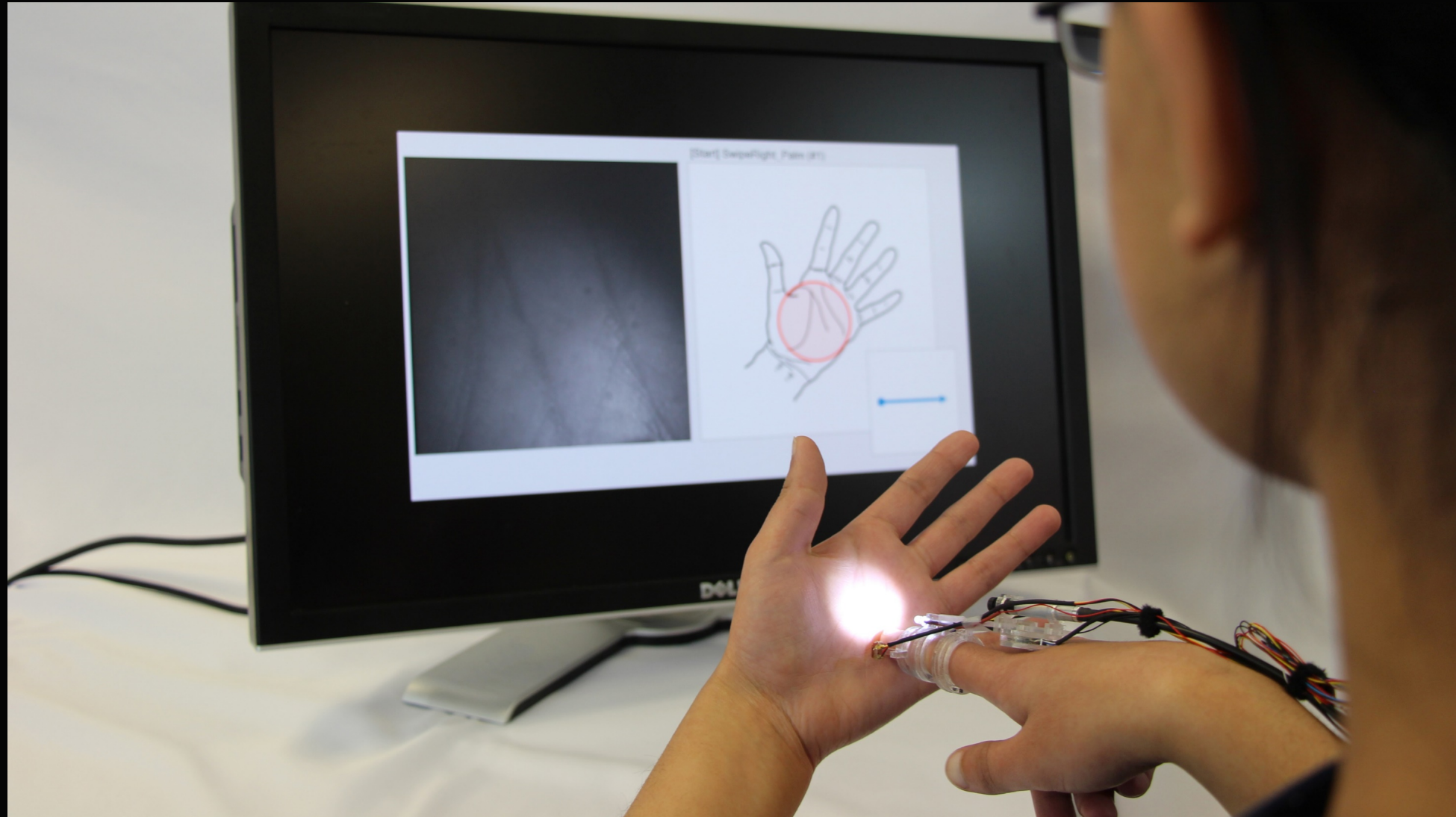
STUDY I

APPARATUS – HW PROTOTYPE V1



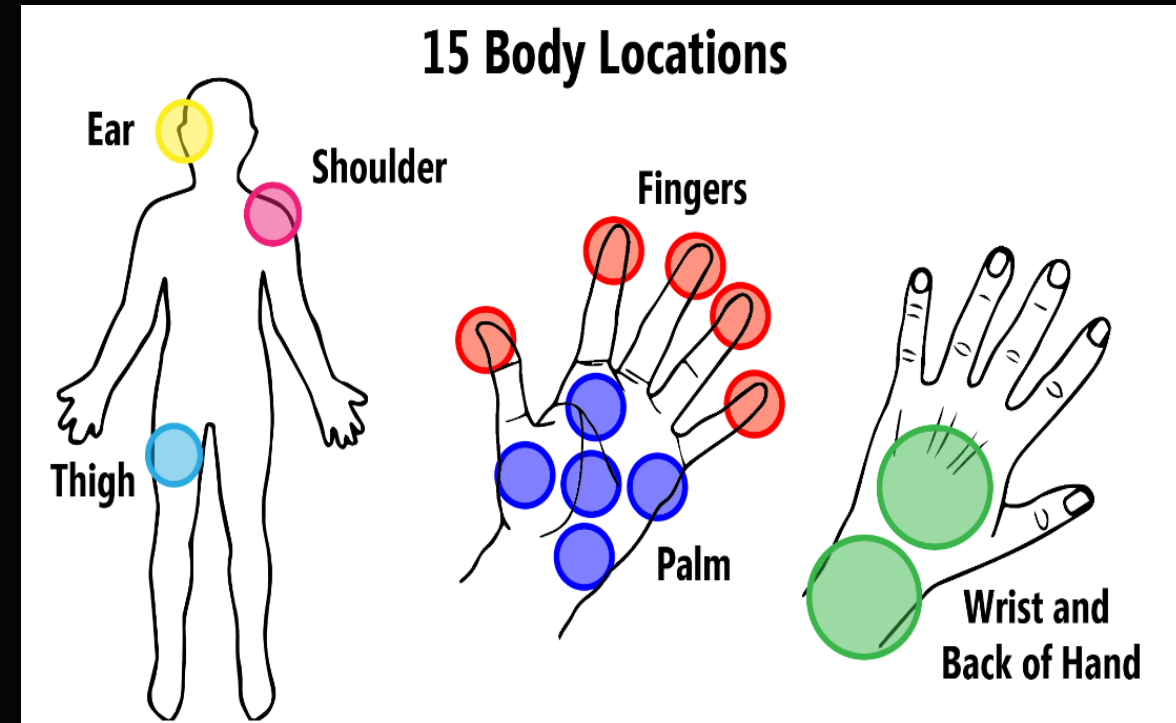
STUDY I

APPARATUS – DATA COLLECTION TOOL



STUDY I PROCEDURE (~90 MIN.)

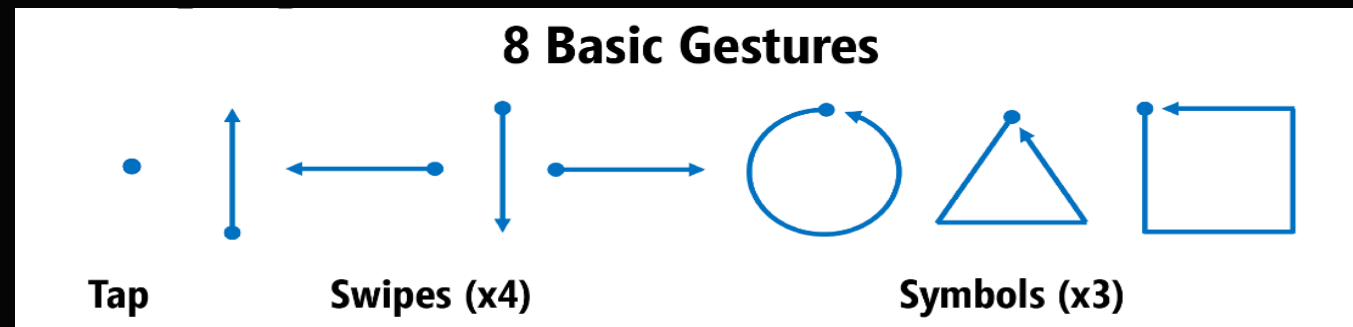
- **Demographic Questionnaire**
- **System Calibration**
- **Data Collection**
 1. Location-specific touches
 - 15 locations x 10 blocks



STUDY I

PROCEDURE (~90 MIN.)

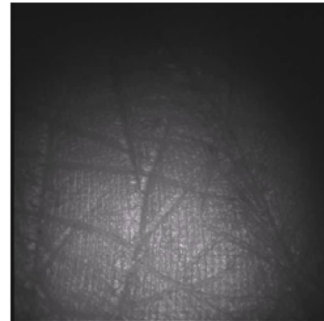
- **Demographic Questionnaire**
- **System Calibration**
- **Data Collection**
 1. Location-specific touches
 2. Location-specific gestures
 - 3 locations (palm, wrist, thigh)
x 8 gestures x 10 blocks



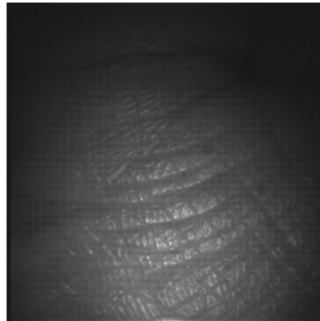
STUDY I

DATA AND ANALYSIS

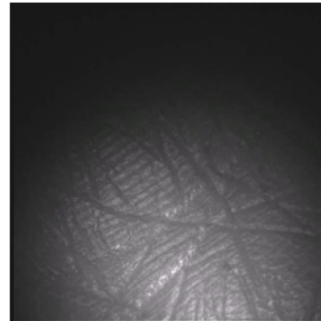
- Data Ex:



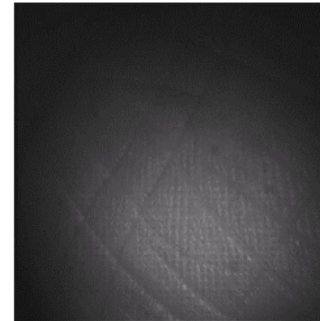
Palm Center



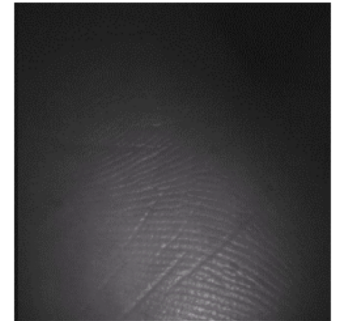
Palm Up



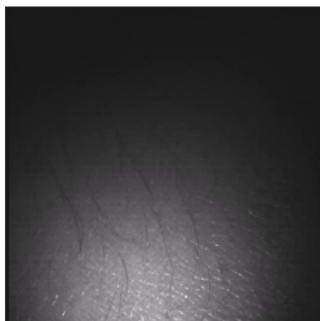
Palm Down



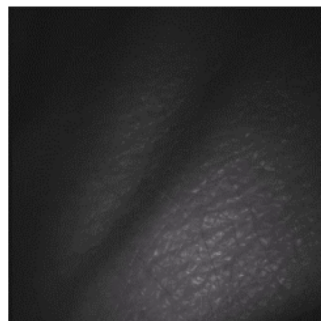
Palm Left



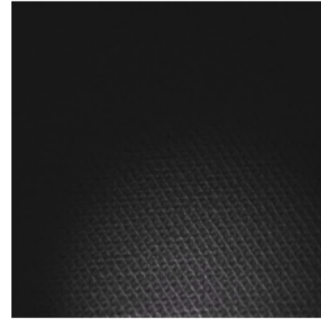
Palm Right



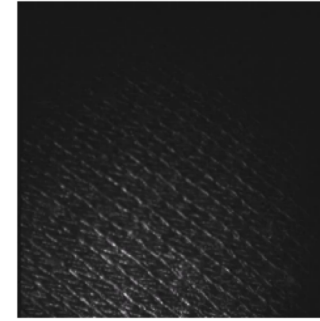
Outer Wrist



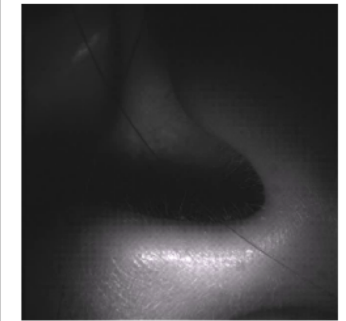
Back of Hand



Thigh



Shoulder



Ear

STUDY I

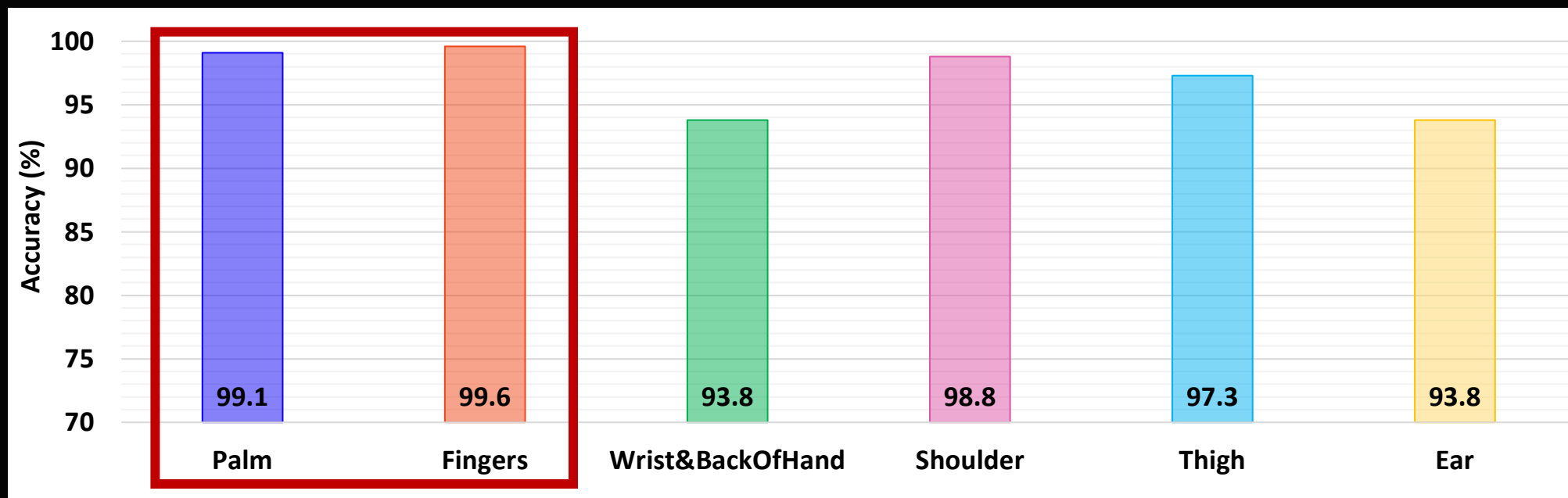
RESULTS – LOCALIZATION

Fine-Grained Localization Avg. Accuracy: 88.7% ($SD=7.0\%$)

(15 classes: PalmCenter, PalmLeft, ...)

Coarse-Grained Localization Avg. Accuracy: 98.0% ($SD=2.3\%$)

(6 classes: palm, fingers, wrist and back of hand, shoulder, thigh, ear)



STUDY I

RESULTS – SENSOR COMBINATIONS

Fine-Grained Accuracy:

- 88.7% with all sensors
- 84.0% with camera only
- 52.9% with all sensors except camera

Coarse-Grained Accuracy:

- 98.0% with all sensors
- 97.5% with camera only
- 87.5% with all sensors except camera

*Coarse-Grained: $p < .001$, $t(23) = 7.12$, $d = 1.92$; Fine-Grained: $p < .001$, $t(23) = 16.74$, $d = 2.99$

STUDY I

RESULTS – GESTURE RECOGNITION

Location-Specific Gestures Avg. Accuracy: **95.7%** ($SD=3.2\%$)

(24 classes: palm-swipeUp, wrist-swipeUp, ..., palm-swipeDown, ...)

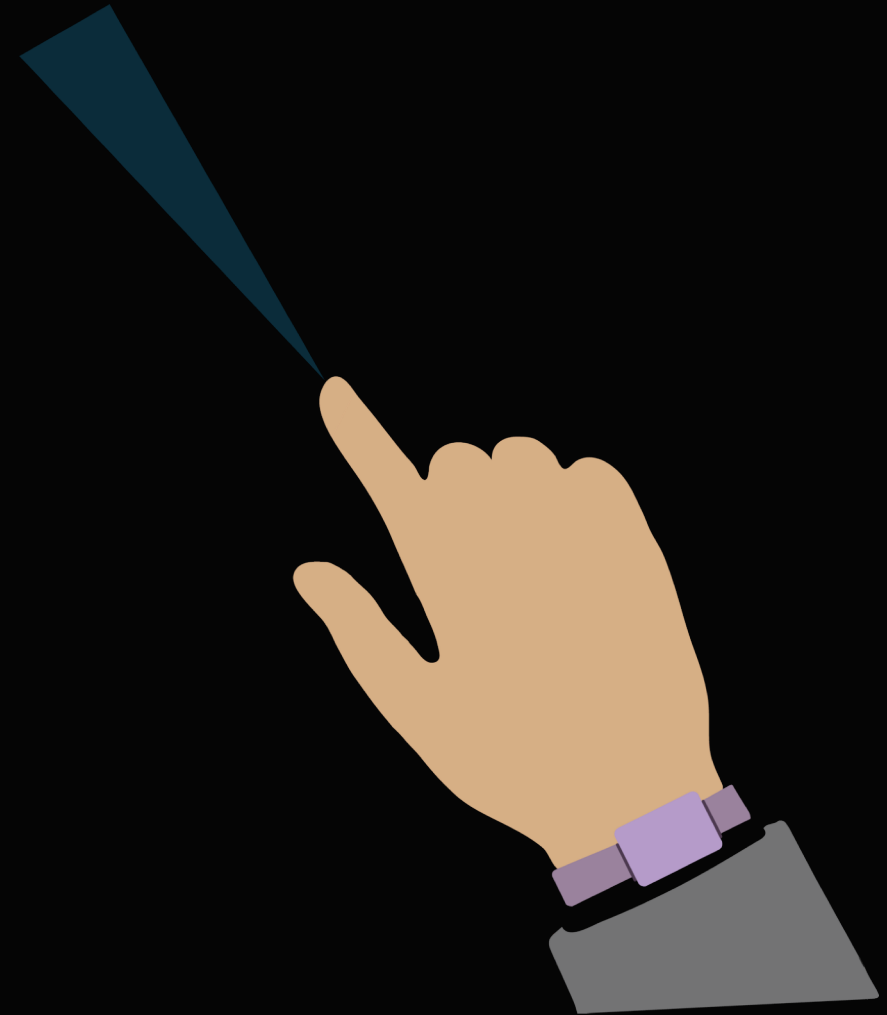
Accuracy for different sensor combinations:

- 84.6% with camera only
- 91% and 91.4% with one IMU (finger vs. wrist)
- 95.1% with two IMU's
- 95.4% with camera and two IMU's

STUDY I

SUMMARY

- **The feasibility evaluation:**
 - Accuracy
 - 88%–98%
 - Efficiency
 - Too slow (approx. 2 sec. per image)
- **Advantages with sensor fusion:**
 - Sensor combination can be optimized





STUDY II

A USABILITY STUDY WITH A REALTIME INTERACTIVE SYSTEM

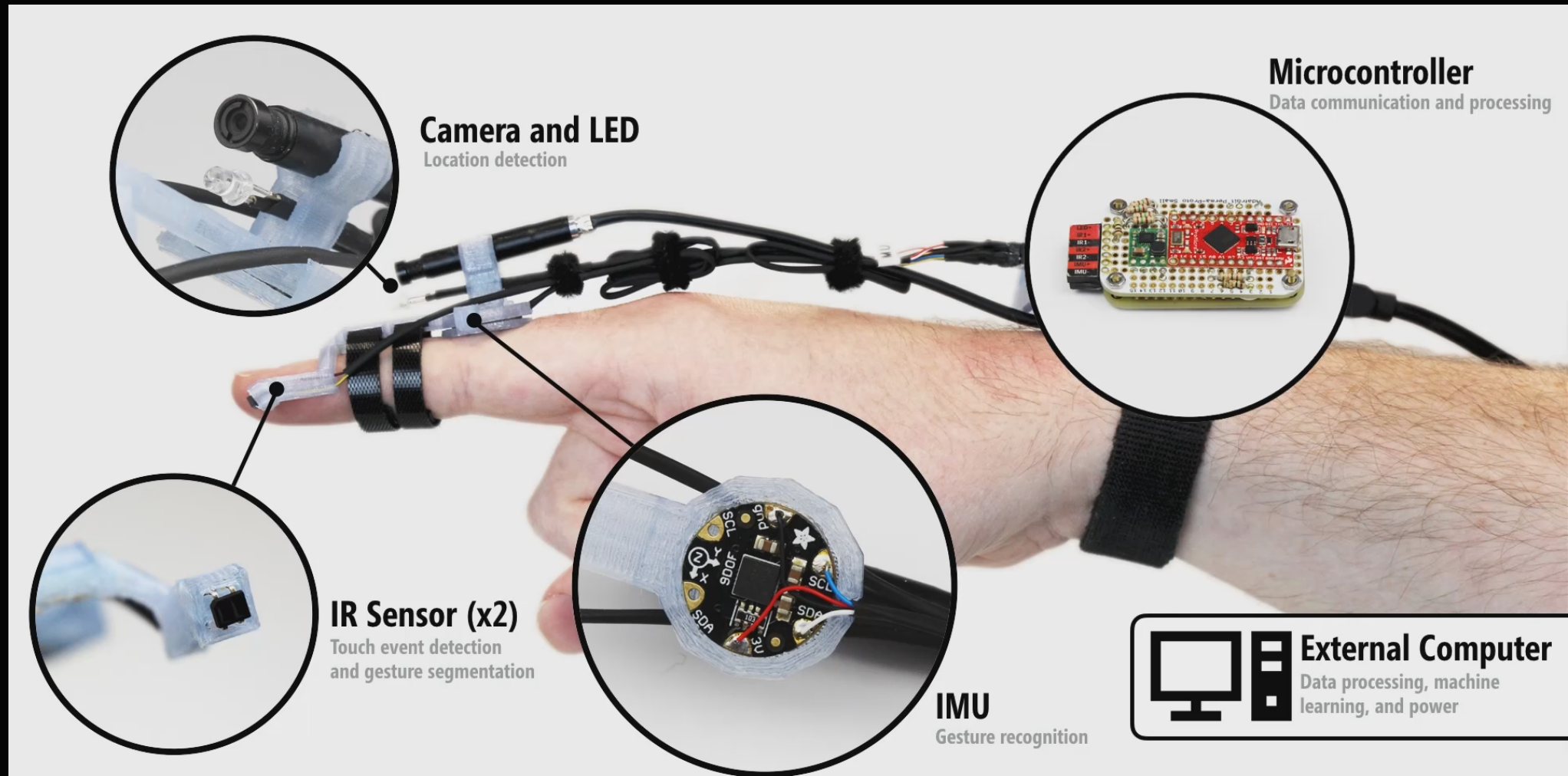
STUDY II

PARTICIPANTS

- **The number of subjects:**
 - 12 (7 female, 5 male)
- **Avg. age:**
 - 46.2 ($SD = 12.0$, range: 29 - 65)
- **Level of vision:**
 - 9 blind, 3 low vision

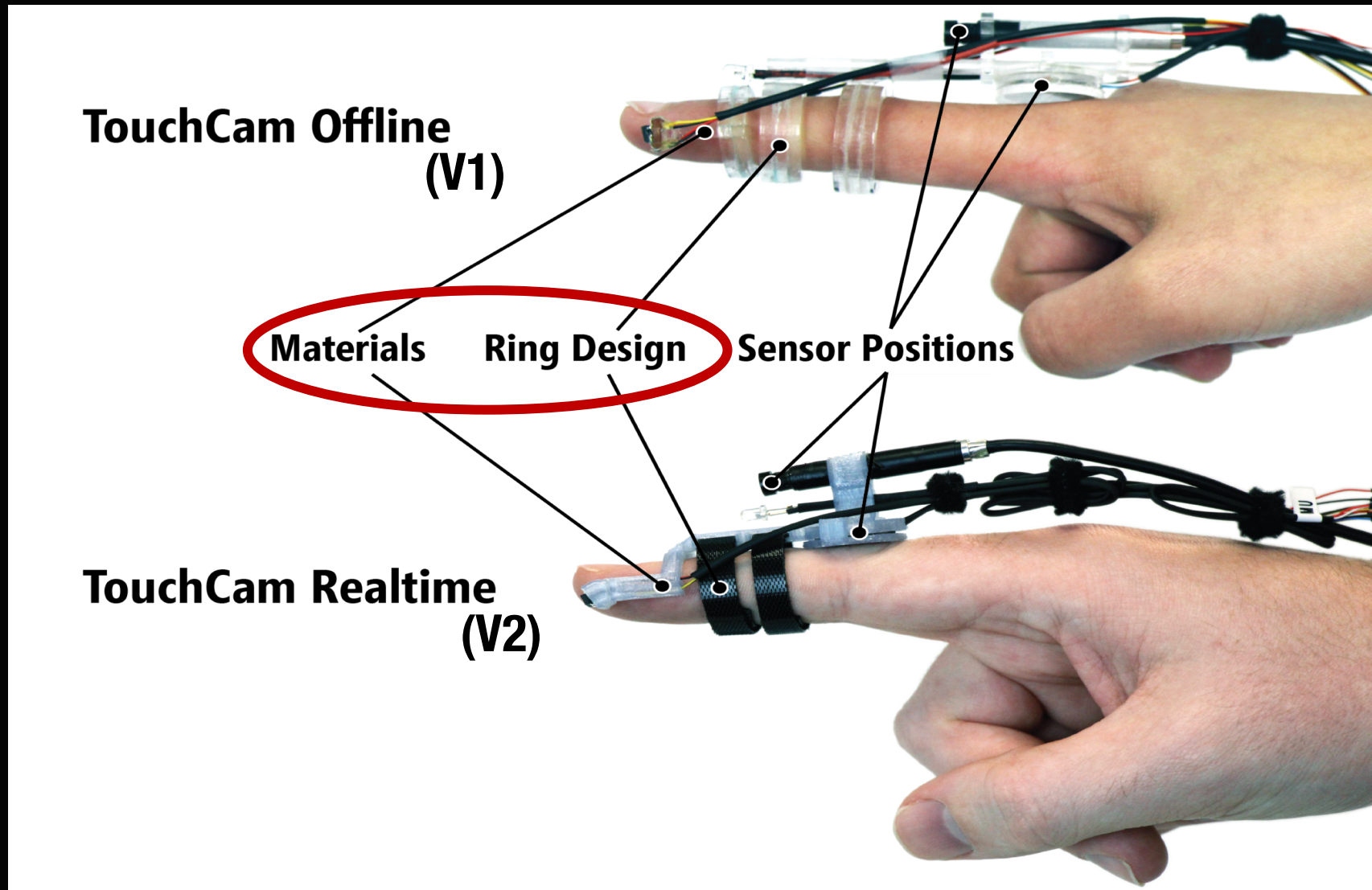
STUDY II

APPARATUS – HW PROTOTYPE V2



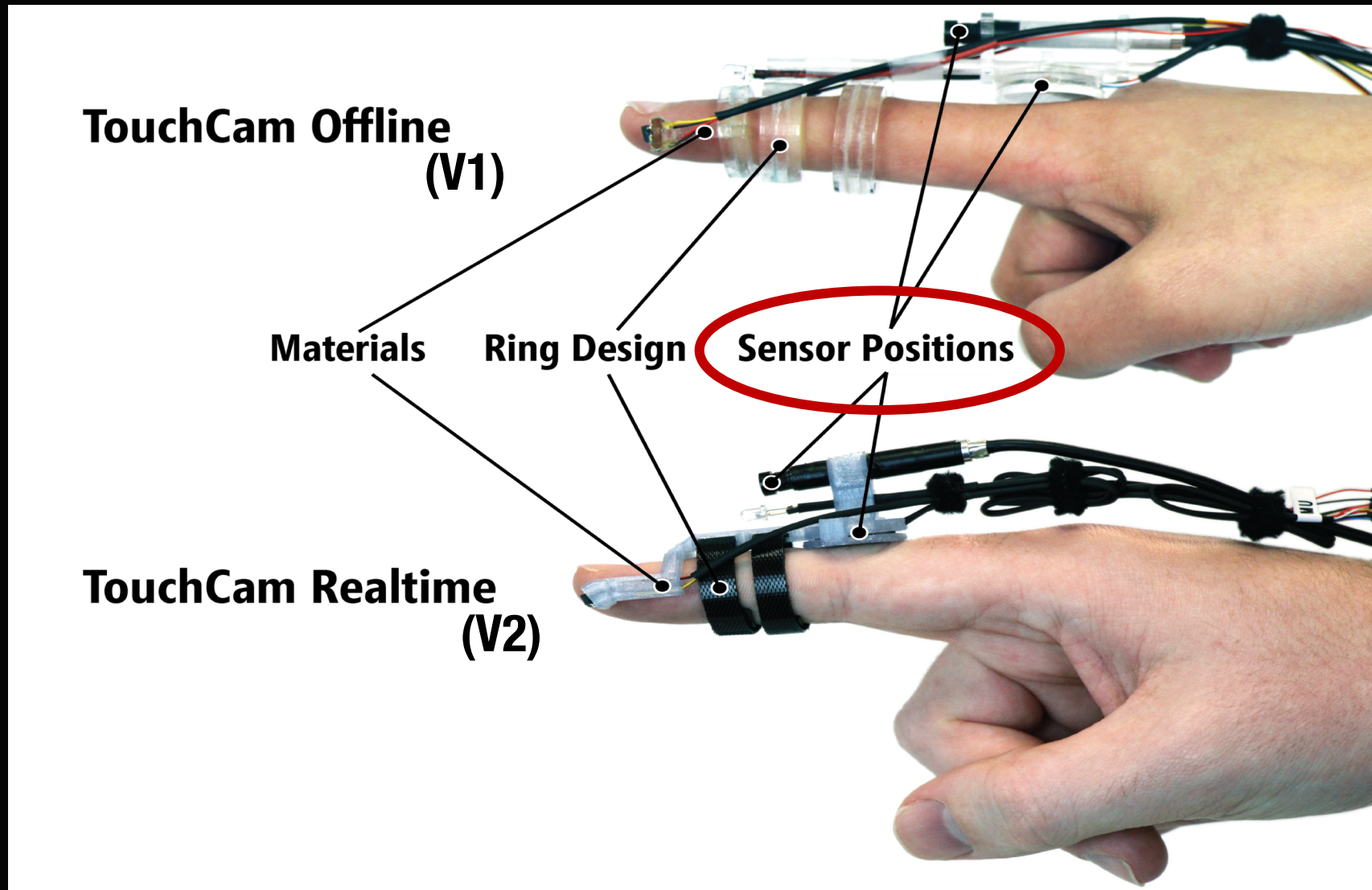
STUDY II

APPARATUS – HW PROTOTYPES



STUDY II

APPARATUS – HW PROTOTYPES



STUDY II

DATA AND ANALYSIS – RECOGNITION

Stage I: Touch Segmentation

Stage II: Feature Extraction

Stage III: Localization

Stage IV: Gesture Classification



Stage III
Localization



Signals

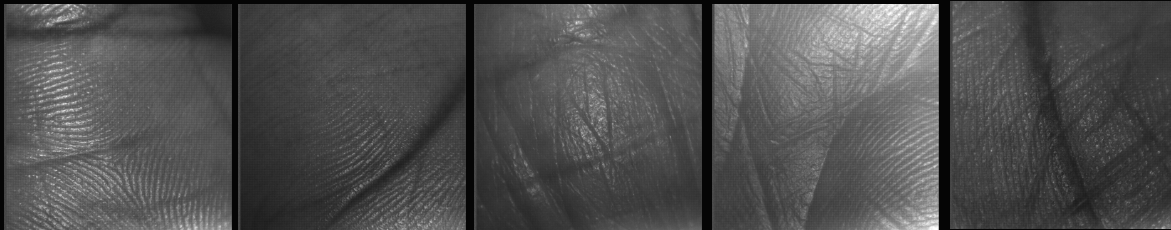


Camera

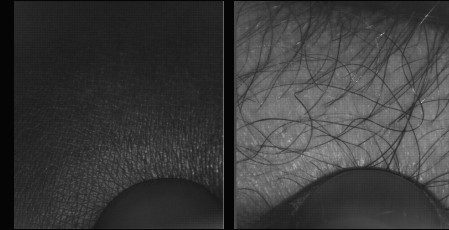
STUDY II

PROCEDURE (~120 MIN.)

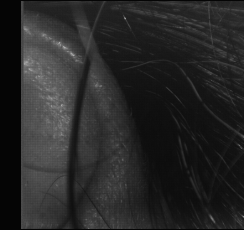
- **Interview**
- **System calibration and training**
- **Tasks**
 1. Location-specific touches
 - 9 locations



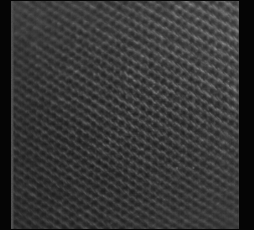
Palm: up, down, left, right, center



Wrist: inner, outer



Ear



Thigh

STUDY II

PROCEDURE (~120 MIN.)

- **Interview**
- **System calibration and training**
- **Tasks**
 1. Location-specific touches
 2. Basic mobile tasks with 3 interaction designs

STUDY II

PROCEDURE (~120 MIN.)

- **Interview**
- **System calibration and training**
- **Tasks**
- **Post-study questionnaires**

STUDY II

RESULTS – LOCALIZATION ACCURACY

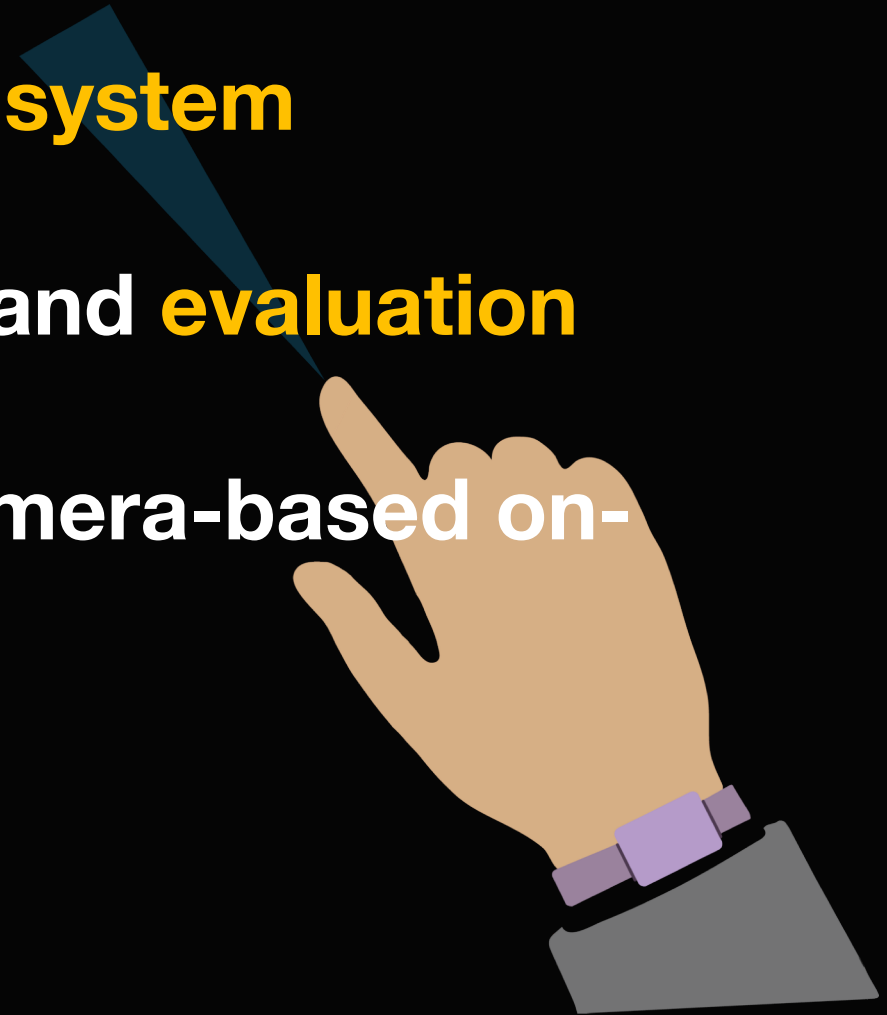
- **Leave-one-out cross-validation** ($N=12$)
 - 81.3% with 9 classes
 - 94.2% with 4 classes (i.e., palm, wrist, ear, thigh)
- **Issues with images** (22%)
 - 13.6% with poor focus
 - 5.4% with insufficient illumination
 - 4.3% with poor contrast
 - 3.2% with target uncaptured



STUDY II

SUMMARY

- Developed **a realtime interactive system**
 - Iterative design process
- Assessed realtime performance and **evaluation with our target population**
- **Identified obstacles** to robust camera-based on-body input recognition



TOUCHCAM – DISCUSSION AND FUTURE WORK

- The benefits

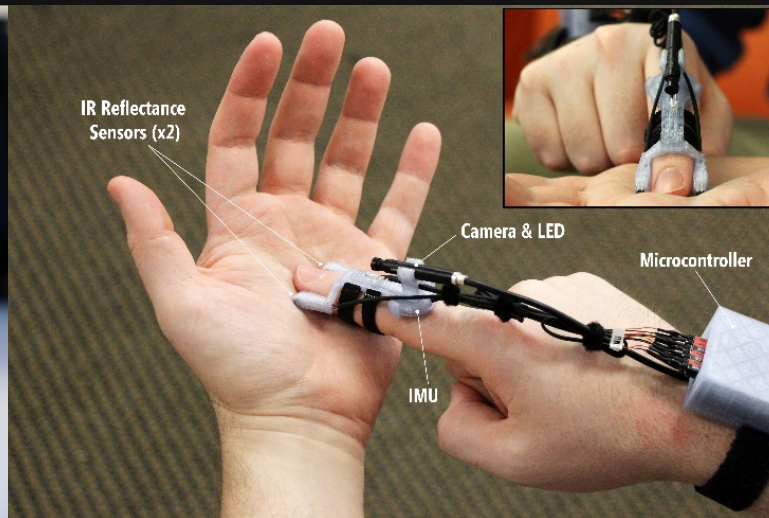
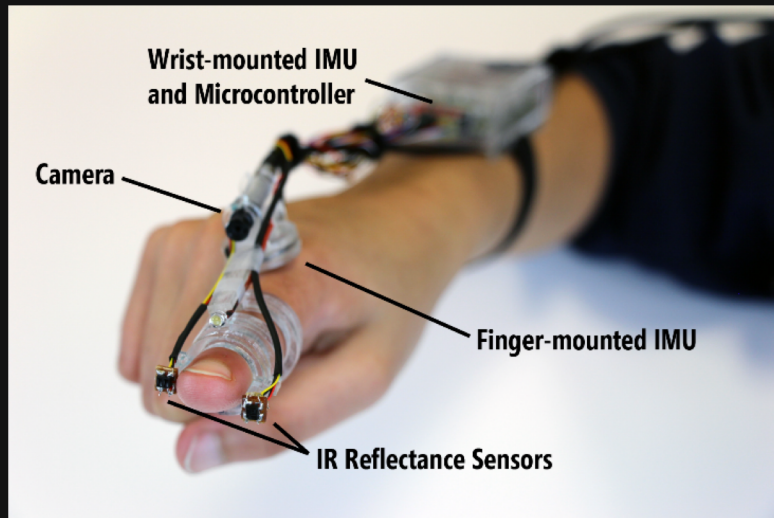
- Expanded on-body input vocabulary

- Location-specific input for context-specific input
 - high degree of flexibility and customization
 - Can be further expanded by supporting multitouch



TOUCHCAM – DISCUSSION AND FUTURE WORK

- The benefits
- The feasibility
 - Physical design
 - Still large, weak computing power
 - Future design should be a small stand-alone device



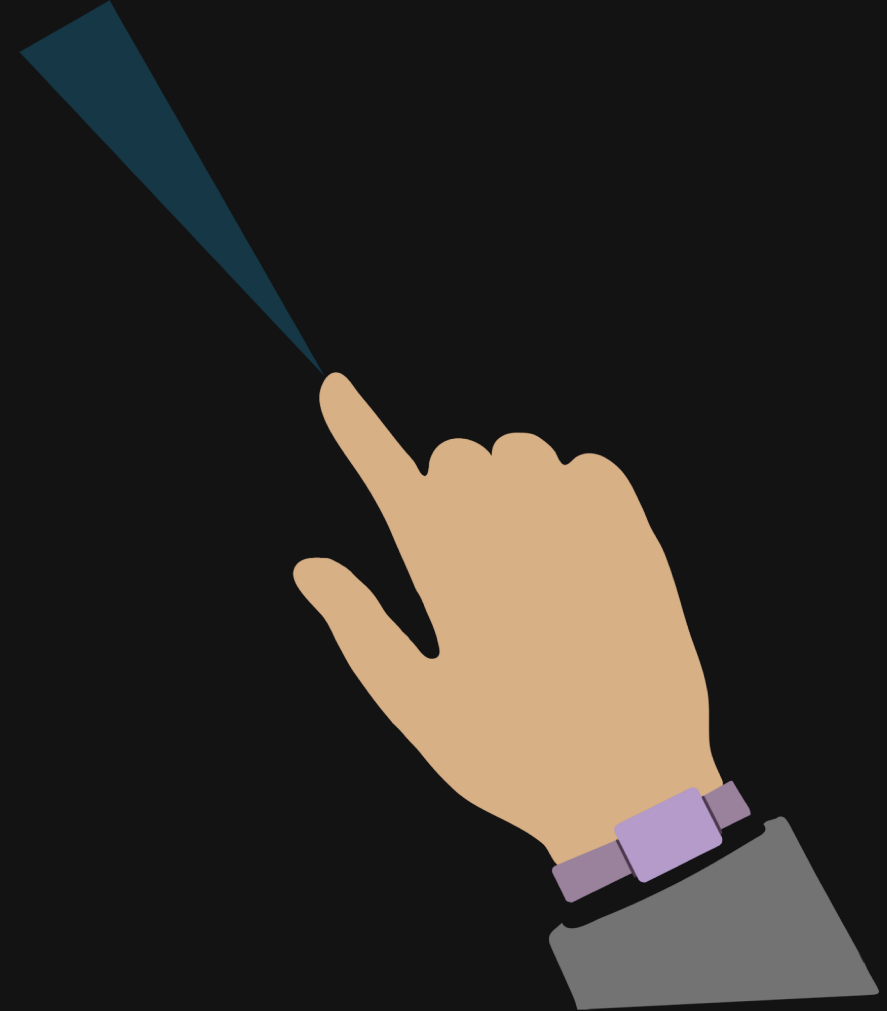
TOUCHCAM – DISCUSSION AND FUTURE WORK

- The benefits
- The feasibility
 - Physical design
 - Performance
 - High accuracy with realtime performance
 - Can be improved with
 - Auto-focus
 - Wide-angle camera with higher resolution
 - Efficient finger-,palmprint recognition



TOUCHCAM – DISCUSSION AND FUTURE WORK

- The benefits
- The feasibility
- The usability
 - Training and calibration take time
 - Can be improved with
 - Bootstrapping the system
 - Training as needed



TOUCHCAM – CONCLUSION

- **Introduced an on-body input sensing system**
 - using sensors worn on the user's gesturing finger
 - for people with visual impairments
- **Demonstrate feasibility with**
 - Accuracy
 - Recognition time
- **Identified design implications and goals for future on-body interfaces**

Thank you 😊

Questions?

You can also reach

Lee Stearns (our first author) at lstearns@umd.edu

or Uran Oh (me) at uran.oh@ewha.ac.kr



TOUCHCAM – REFERENCES

Localization:

Stearns, L., Oh, U., Cheng, B. J., Findlater, L., Ross, D., Chellappa, R., & Froehlich, J. E. (2016, December). Localization of skin features on the hand and wrist from small image patches. In Pattern Recognition (ICPR), 2016 23rd International Conference on (pp. 1003-1010). IEEE.

Qualitative Analysis:

Oh, U., Stearns, L., Pradhan, A., Froehlich, J. E., & Findlater, L. (2017, October). Investigating Microinteractions for People with Visual Impairments and the Potential Role of On-Body Interaction. In *Proceedings of the 19th International ACM SIGACCESS Conference on Computers and Accessibility* (pp. 22-31). ACM.

