CookAR

Affordance Augmentations in Wearable AR to Support Kitchen Tool Interactions for People with Low Vision

Jaewook Lee¹, Andrew D. Tjahjadi¹, Jiho Kim¹, Junpu Yu¹, Minji Park², Jiawen Zhang¹, Jon E. Froehlich¹, Yapeng Tian³, Yuhang Zhao⁴

University of Washington¹, Sungkyunkwan University², University of Texas at Dallas³, University of Wisconsin–Madison⁴













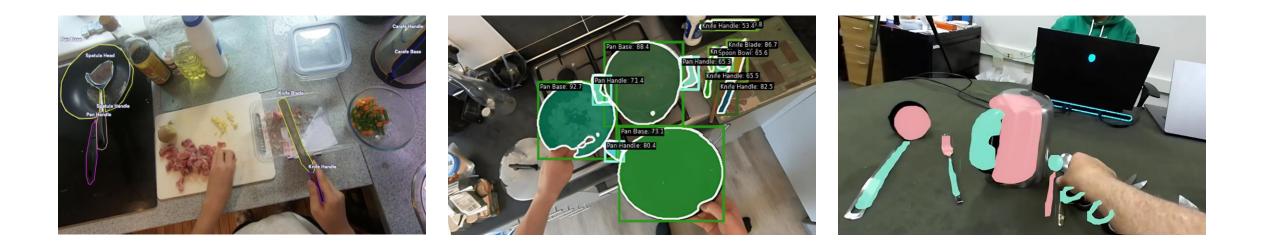






We introduce **CookAR**, a wearable AR prototype that recognizes and augments cooking tool affordances in near real-time to support LV cooking.

The CookAR System



- 01 A custom egocentric kitchen tool affordance dataset of 10,152 images.
- **02** A fine-tuned affordance segmentation model.

03 A wearable AR research prototype capable of overlaying visual augmentations.

Data Collection

We start with the *Epic Kitchens* dataset, an egocentric video dataset of sighted people cooking.



Damen et al. The EPIC-KITCHENS Dataset: Collection, Challenges and Baselines

Data Collection

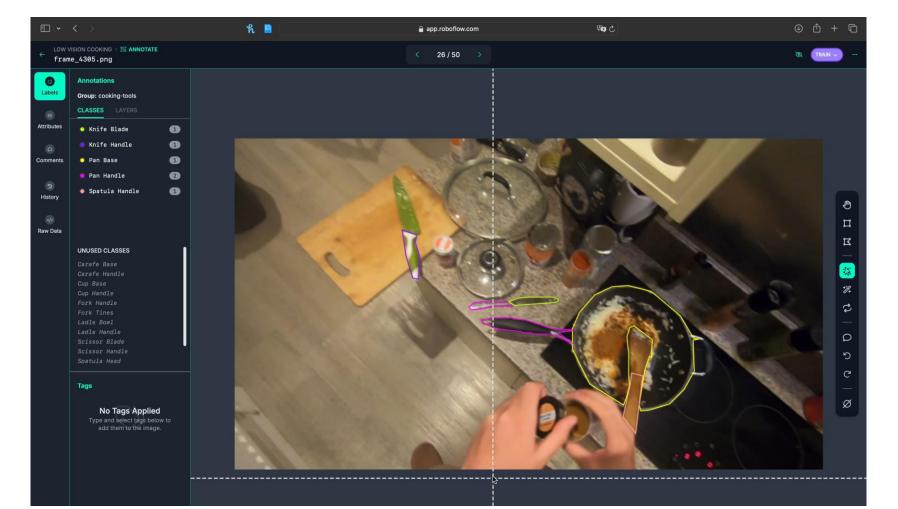
We first use YOLOv8 to find key frames in the Epic Kitchens dataset, followed by manual filtering.



YOLOv8 inferencing on Damen et al.'s video wall

Data Annotation

We then used Roboflow and the Segment Anything model (SAM) to manually label selected frames.



Data Annotation

We labeled <u>18</u> distinct affordance classes of kitchen tools commonly used by BLV individuals.



Knife Blade & Handle



Scissor Blade & Handle



Pan Base & Handle



Ladle Bowl & Handle



Cup Base & Handle



Fork Tines & Handle



Spatula Head & Handle



Carafe Base & Handle



Model Fine-Tuning

We fine-tuned the *RTMDet-ins-I* model, the current state-of-the-art in real-time instance segmentation.

Undergoing fine-tuning on a dataset with affordance annotations allows it to mimic an affordance segmentation model's capabilities.



Example inferencing result of our custom RTMDet-ins-l-cook model.

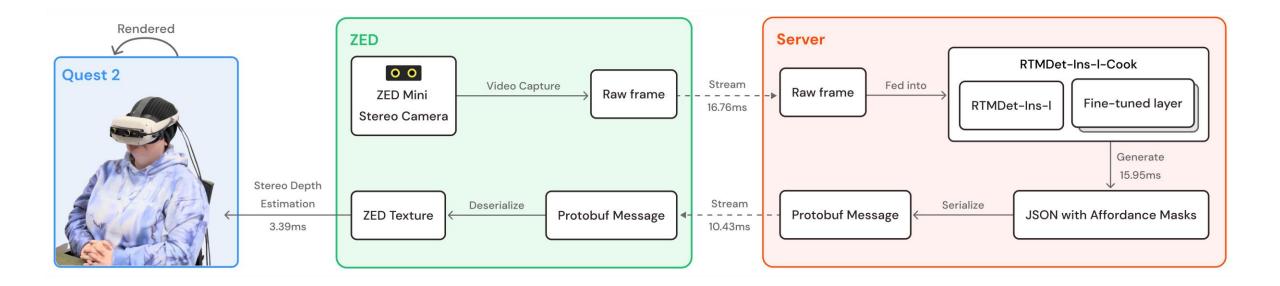


AR Prototype

We built a custom stereo video see-through AR system by combining the ZED Mini stereo camera with an Oculus Quest 2 headset.

The ZED Mini stereo camera enables CookAR to perform binocular depth estimation.

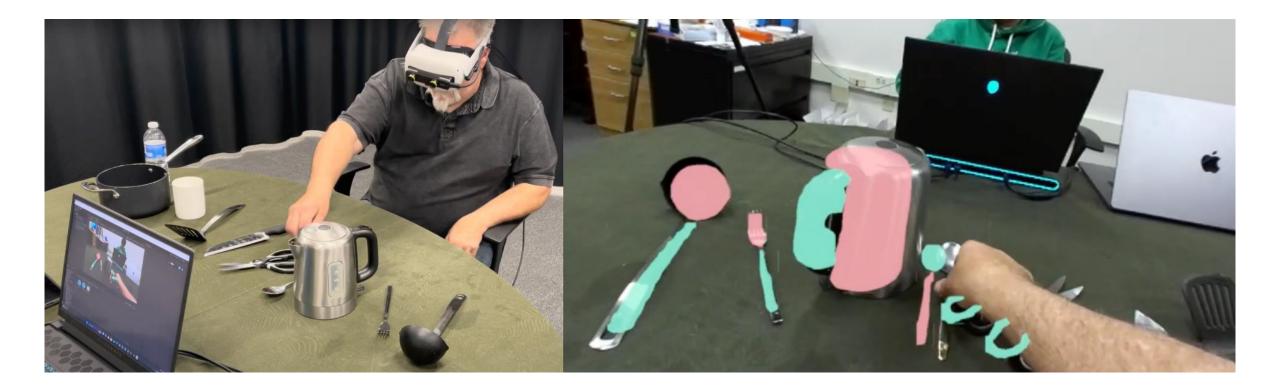
We stream raw video frames from ZED to an external server for heavy CV.

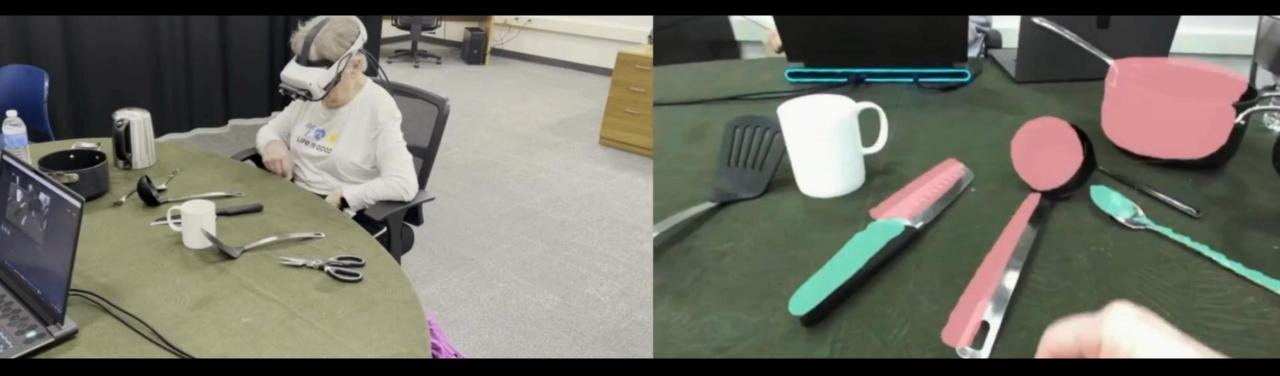


AR Prototype

The CookAR AR prototype displays affordance augmentations:

- **Green** (hexcode #3BE8B0) indicates a graspable area.
- **Red** (#FC626A) indicates a risky area.





User Study

We conducted a three-part lab study with 10 low vision participants.



Whole Object Augmentations

CookAR with Affordance Augmentations

Part 1 - comparing three conditions in a tool grabbing task.

- 1. Real world baseline (i.e., without CookAR),
- 2. Augmentation baseline (i.e., whole object augmentations),
- 3. CookAR (i.e., affordance augmentations)

User Study

Part 2 - cooking macaroni and cheese using CookAR with affordance augmentations.



User Study

Part 3 – brainstorming and co-designing future designs and applications of CookAR.



Outline Hazard



Outline Exact Hazard + Solid Grabbable



Solid Grabbable



Arrow on Hazard



Outline Hazard + Solid Grabbable



Arrow on Grabbable



Outline Exact Hazard

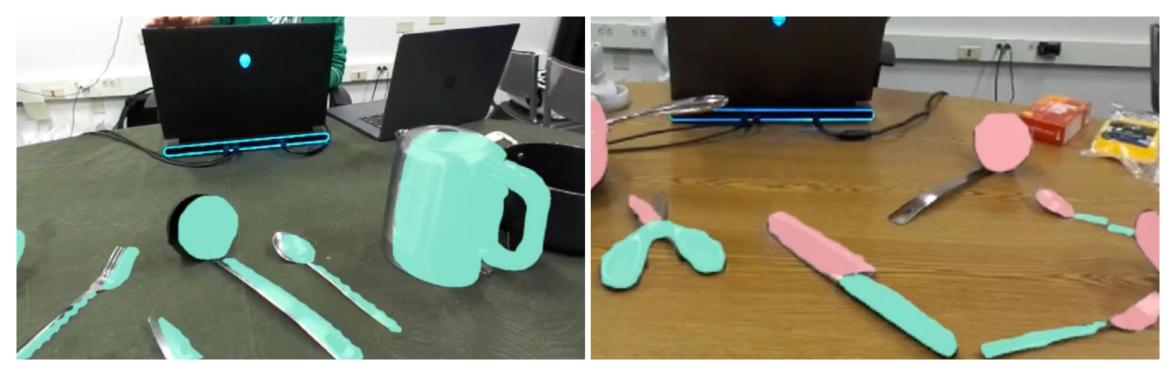


Warning System

Affordance vs. Whole Object Augmentations

CookAR should render augmentations tailored to users' intent and reduce distraction.

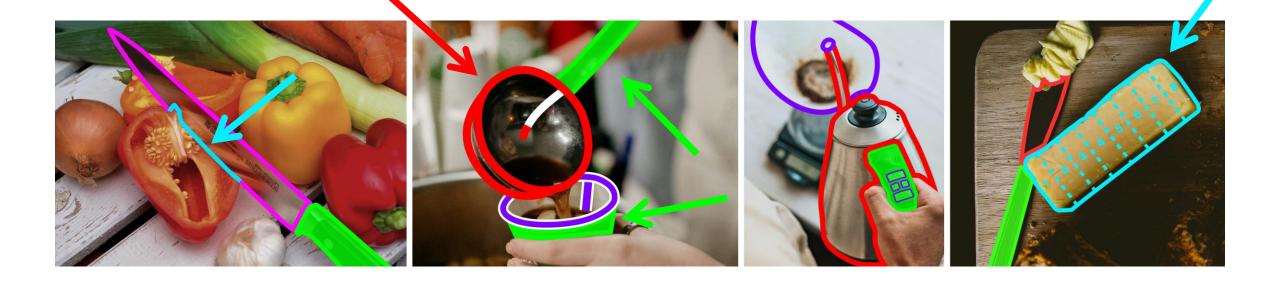
- For complex objects and hand-object manipulations, **affordance augmentations** are better.
 - Gardening, playing board games, interacting with appliances, etc.
- For general visual perception, whole object augmentations are better.
 - Avoiding obstacles, locating an object, etc.



Desired Augmentation Designs

Participants desire the following augmentation designs:

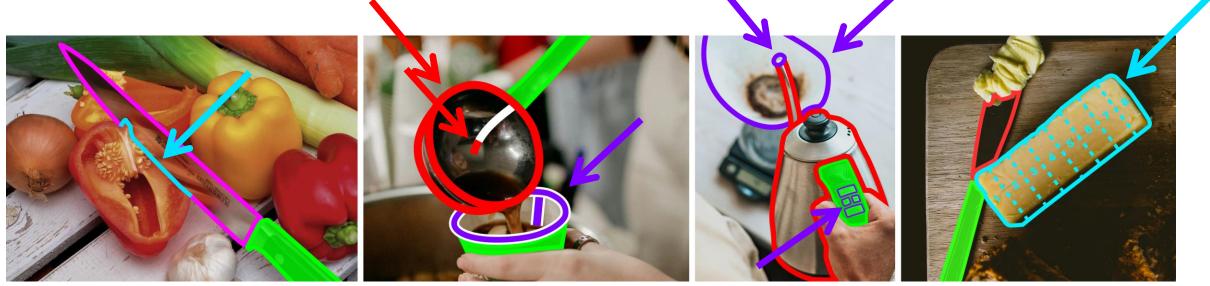
- Combine solid and outline augmentations
- Enhance color contrast
- Auditory feedback
- Personalization



Additional Tool Affordances

Beyond grabbable and hazardous areas, participants identified five additional tool affordances:

- Entry
- Exit
- Containment
- Intersection
- Activation





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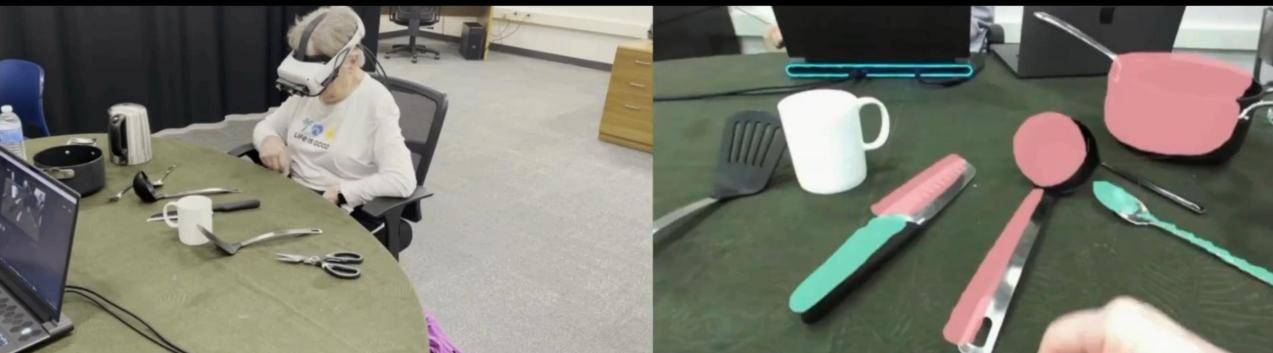














Thanks for listening!

Let's Connect!

Email	jaewook4@cs.washington.edu
Website	https://jaewook-lee.com
Twitter	https://twitter.com/jaewook_jae





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